

ON POSITIVE PERIODIC SOLUTIONS OF LOTKA-VOLTERRA COMPETITION SYSTEMS WITH DEVIATING ARGUMENTS

XIANHUA TANG AND XINGFU ZOU

(Communicated by Carmen C. Chicone)

ABSTRACT. By using Krasnoselskii's fixed point theorem, we prove that the following periodic n -species Lotka-Volterra competition system with multiple deviating arguments

$$(*) \quad \dot{x}_i(t) = x_i(t) \left[r_i(t) - \sum_{j=1}^n a_{ij}(t)x_j(t - \tau_{ij}(t)) \right], \quad i = 1, 2, \dots, n,$$

has at least one positive ω -periodic solution provided that the corresponding system of linear equations

$$(**) \quad \sum_{j=1}^n \bar{a}_{ij} x_j = \bar{r}_i, \quad i = 1, 2, \dots, n,$$

has a positive solution, where $r_i, a_{ij} \in C(\mathbf{R}, [0, \infty))$ and $\tau_{ij} \in C(\mathbf{R}, \mathbf{R})$ are ω -periodic functions with

$$\bar{r}_i = \frac{1}{\omega} \int_0^\omega r_i(s) ds > 0; \quad \bar{a}_{ij} = \frac{1}{\omega} \int_0^\omega a_{ij}(s) ds \geq 0, \quad i, j = 1, 2, \dots, n.$$

Furthermore, when $a_{ij}(t) \equiv a_{ij}$ and $\tau_{ij}(t) \equiv \tau_{ij}$, $i, j = 1, \dots, n$, are constants but $r_i(t)$, $i = 1, \dots, n$, remain ω -periodic, we show that the condition on $(**)$ is also necessary for $(*)$ to have at least one positive ω -periodic solution.

1. INTRODUCTION

In recent years, various delay differential equation models have been proposed in the study of ecological systems, population dynamics and infectious diseases. One of the most celebrated models for dynamics of population is the Lotka-Volterra system. Due to its theoretical and practical significance, the Lotka-Volterra system have been studied extensively [2]–[12], [14]–[19], [21]–[25]. In particular, [4]–[7], [14], [16]–[19], [21]–[23] investigated the existence of periodic solutions of some special cases of the following *periodic* n -species Lotka-Volterra competition system with

Received by the editors August 13, 2004 and, in revised form, April 29, 2005.

2000 *Mathematics Subject Classification*. Primary 34K13; Secondary 34K20, 92D25.

Key words and phrases. Positive periodic solution, Lotka-Volterra competition system.

The first author was supported in part by NNSF of China (No. 10471153), and the second author was supported in part by the NSERC of Canada and by a Faculty of Science Dean's Start-Up Grant at the University of Western Ontario.

several deviating arguments:

$$(1.1) \quad \dot{x}_i(t) = x_i(t) \left[r_i(t) - \sum_{j=1}^n a_{ij}(t)x_j(t - \tau_{ij}(t)) \right], \quad i = 1, 2, \dots, n,$$

where $r_i, a_{ij} \in C(\mathbf{R}, [0, \infty))$ and $\tau_{ij} \in C(\mathbf{R}, \mathbf{R})$ are ω -periodic functions ($\omega > 0$) with

$$(1.2) \quad \bar{r}_i = \frac{1}{\omega} \int_0^\omega r_i(s)ds > 0; \quad \bar{a}_{ij} = \frac{1}{\omega} \int_0^\omega a_{ij}(s)ds \geq 0, \quad i, j = 1, 2, \dots, n.$$

For example, Shibata and Saito [21] studied a two-species delay Lotka-Volterra competition system and showed that the delays in the system can lead to chaotic behavior. When $n = 1$, (1.1) reduces to the following delayed periodic logistic equation:

$$(1.3) \quad \dot{x}(t) = x(t) [r(t) - a(t)x(t - \tau(t))].$$

It was shown in Li [17] that Eq. (1.3) always has a positive ω -periodic solution if $r, a, \tau \in C(\mathbf{R}, [0, \infty))$ are ω -periodic functions with $\int_0^\omega r(s)ds > 0$ and $\int_0^\omega a(s)ds > 0$.

Recently, by using the method of coincidence degree, Fan et al. [7] and Li [18] investigated the existence of periodic solutions of Eq. (1.1) and established the following two results respectively.

Theorem 1.1 ([7]). *Assume that $\bar{a}_{ii} > 0$ and*

$$(1.4) \quad \bar{r}_i > \sum_{j \neq i} \frac{\bar{a}_{ij}\bar{r}_j}{\bar{a}_{jj}} e^{2\bar{r}_j\omega}, \quad i = 1, 2, \dots, n.$$

Then Eq. (1.1) has at least one positive periodic solution of periodic ω .

Theorem 1.2 ([18]). *Assume that $\tau_{ii}(t) = 0, i = 1, 2, \dots, n$, and that*

(C): *the linear system*

$$(1.5) \quad \sum_{j=1}^n \bar{a}_{ij} x_j = \bar{r}_i, \quad i = 1, 2, \dots, n,$$

has a positive solution.

In addition, suppose that

$$(1.6) \quad \bar{r}_i > \sum_{j \neq i} \bar{a}_{ij} \max_{0 \in [0, \omega]} \left| \frac{r_j(t)}{a_{jj}(t)} \right|, \quad i = 1, 2, \dots, n.$$

Then Eq. (1.1) has at least one positive ω -periodic solution.

In the the proof of Theorem 1.2, the author took advantage of the fact that there is no deviating argument in the negative feedback terms $a_{ii}(t)x_i(t), i = 1, 2, \dots, n$. Thus, Theorem 1.2 may fail for Eq. (1.1) when $\tau_{ii}(t) \neq 0$. Furthermore, by Lemma 4.1 in [11], it is not difficult to see that condition (1.4) implies (C). But conditions (1.4) and (1.6) are independent in the sense that neither of them implies the other, and therefore, Theorems 1.1 and 1.2 are complementary.

In both Theorems 1.1 and 1.2, (C) is an essential condition. Obviously, when $a_{ij}(t) \equiv a_{ij}, r_i(t) \equiv r_i, i, j = 1, 2, \dots, n$, are all constants, (C) is also a sufficient and necessary condition for Eq. (1.1) to have a trivial positive periodic solution

(i.e. positive equilibrium). Also, note that as a special case of (1.1), Eq. (1.3) always has a positive ω -periodic solution provided that

$$(C_0): \bar{r} = \int_0^\omega r(s)ds > 0 \text{ and } \bar{a} = \int_0^\omega a(s)ds > 0,$$

which is implied by (C) under (1.2) in this case (since Eq. (1.5) becomes $\bar{a}x = \bar{r}$). Motivated by these two observations, we conjecture that (1.4) and (1.6) may not be necessary, and condition (C) may only be enough to guarantee that (1.1) has at least one positive ω -periodic solution.

The purpose of this paper is to give a positive answer to the above conjecture. More precisely, in Section 2, we prove that if (C) holds, then Eq. (1.1) has at least one positive ω -periodic solution. Furthermore, when $a_{ij}(t) \equiv a_{ij}$ and $\tau_{ij}(t) \equiv \tau_{ij}$, \dots, n are constants but $r_i(t)$, $i = 1, \dots, n$, remain ω -periodic, we show that (C) is even a sufficient and necessary condition for Eq. (1.1) to have at least one positive ω -periodic solution.

Throughout of this paper, we say a vector $x = (x_1, x_2, \dots, x_n)^T$ is positive if $x_i > 0$, $i = 1, 2, \dots, n$.

2. MAIN RESULTS

For convenience, we introduce the definition of cone and the well-known Krasnoselskii's fixed point theorem.

Definition 2.1. Let X be a Banach space and let P be a closed, nonempty subset of X . P is a cone if

- (i) $\alpha x + \beta y \in P$ for all $x, y \in P$ and all $\alpha, \beta \geq 0$;
- (ii) $x, -x \in P$ imply $x = 0$.

Lemma 2.2 (Krasnoselskii, [13]). *Let X be a Banach space, and let $P \subset X$ be a cone in X . Assume that Ω_1, Ω_2 are open bounded subsets of X with $0 \in \Omega_1 \subset \bar{\Omega}_1 \subset \Omega_2$, and let*

$$\varphi : P \cap (\bar{\Omega}_2 \setminus \Omega_1) \rightarrow P$$

be a completely continuous operator such that either

- (i) $\|\varphi x\| \leq \|x\|$, $\forall x \in P \cap \partial\Omega_1$ and $\|\varphi x\| \geq \|x\|$, $\forall x \in P \cap \partial\Omega_2$;

or

- (ii) $\|\varphi x\| \geq \|x\|$, $\forall x \in P \cap \partial\Omega_1$ and $\|\varphi x\| \leq \|x\|$, $\forall x \in P \cap \partial\Omega_2$. Then φ has a fixed point in $P \cap (\bar{\Omega}_2 \setminus \Omega_1)$.

Let

$$(2.1) \quad X = \{x(t) = (x_1(t), x_2(t), \dots, x_n(t))^T \in C(\mathbf{R}, \mathbf{R}^n) : x(t + \omega) = x(t)\},$$

$$(2.2) \quad \|x\| = \sum_{j=1}^n |x_j|_0, \quad |x_j|_0 = \max_{t \in [0, \omega]} |x_j(t)|, \quad i = 1, 2, \dots, n.$$

Then X is Banach space endowed with the above norm $\|\cdot\|$. If $x(t) = (x_1(t), x_2(t), \dots, x_n(t))^T \in X$ is a solution of Eq. (1.1), then

$$(2.3) \quad \begin{aligned} & \left[x_i(t) \exp \left(- \int_0^t r_i(s) ds \right) \right]' \\ & = - \exp \left(- \int_0^t r_i(s) ds \right) x_i(t) \sum_{j=1}^n a_{ij}(t) x_j(t - \tau_{ij}(t)), \quad i = 1, 2, \dots, n. \end{aligned}$$

Integrating both sides of (2.3) over $[t, t + \omega]$, we obtain

$$(2.4) \quad x_i(t) = \int_t^{t+\omega} G_i(t, s)x_i(s) \sum_{j=1}^n a_{ij}(s)x_j(s - \tau_{ij}(s))ds, \quad i = 1, 2, \dots, n,$$

where

$$(2.5) \quad G_i(t, s) = \frac{1}{1 - e^{-\bar{r}_i\omega}} \exp\left(-\int_t^s r_i(\xi)d\xi\right), \quad i = 1, 2, \dots, n.$$

Let $\sigma = \min\{e^{-\bar{r}_i\omega} : i = 1, 2, \dots, n\}$. Now, choose the cone defined by

$$(2.6) \quad P = \{x(t) = (x_1(t), x_2(t), \dots, x_n(t))^T \in X : x_i(t) \geq \sigma|x_i|_0, i = 1, 2, \dots, n\},$$

and define an operator $\Phi : X \rightarrow X$ by

$$(2.7) \quad (\Phi x)(t) = ((\Phi x)_1(t), (\Phi x)_2(t), \dots, (\Phi x)_n(t))^T,$$

where

$$(2.8) \quad (\Phi x)_i(t) = \int_t^{t+\omega} G_i(t, s)x_i(s) \sum_{j=1}^n a_{ij}(s)x_j(s - \tau_{ij}(s))ds, \quad i = 1, 2, \dots, n.$$

By (2.4), it is easy to verify that $x = x(t) \in X$ is a ω -periodic solution of Eq. (1.1) provided x is a fixed point of Φ .

Lemma 2.3. *The mapping Φ maps P into P , i.e. $\Phi P \subset P$.*

Proof. It is easy to see that for $t \leq s \leq t + \omega$,

$$(2.9) \quad A_i := \frac{e^{-\bar{r}_i\omega}}{1 - e^{-\bar{r}_i\omega}} \leq G_i(t, s) \leq \frac{1}{1 - e^{-\bar{r}_i\omega}} := B_i, \quad i = 1, 2, \dots, n.$$

From (2.8) and (2.9), we have for $x \in P$

$$|(\Phi x)_i|_0 \leq B_i \int_0^\omega x_i(s) \sum_{j=1}^n a_{ij}(s)x_j(s - \tau_{ij}(s))ds$$

and

$$(\Phi x)_i(t) \geq A_i \int_0^\omega x_i(s) \sum_{j=1}^n a_{ij}(s)x_j(s - \tau_{ij}(s))ds \geq \frac{A_i}{B_i}|(\Phi x)_i|_0 \geq \sigma|(\Phi x)_i|_0.$$

Hence, $\Phi P \subset P$. The proof is completed. □

Lemma 2.4. *$\Phi : P \rightarrow P$ is completely continuous.*

Proof. Set

$$f_i(t, x_t) = x_i(t) \sum_{j=1}^n a_{ij}(t)x_j(t - \tau_{ij}(t)), \quad i = 1, 2, \dots, n.$$

We first show that Φ is continuous. For any $L > 0$ and $\varepsilon > 0$, there exists a $\delta > 0$ such that for $\phi, \psi \in X, \|\phi\| \leq L, \|\psi\| \leq L$, and $\|\phi - \psi\| < \delta$ imply

$$(2.10) \quad \max_{s \in [0, \omega]} |f_i(s, \phi_s) - f_i(s, \psi_s)| < \frac{\varepsilon}{nB\omega}, \quad i = 1, 2, \dots, n,$$

where $B = \max_{1 \leq i \leq n} B_i$. If $x, y \in X$ with $\|x\| \leq L, \|y\| \leq L$, and $\|x - y\| \leq \delta$, then from (2.8), (2.9) and (2.10), we have

$$\begin{aligned} |(\Phi x)_i - (\Phi y)_i|_0 &\leq \int_t^{t+\omega} |G_i(t, s)| |f_i(s, x_s) - f_i(s, y_s)| ds \\ &\leq B \int_0^\omega |f_i(s, x_s) - f_i(s, y_s)| ds \\ &< \frac{\varepsilon}{n}, \quad i = 1, 2, \dots, n. \end{aligned}$$

This yields

$$\|\Phi x - \Phi y\| = \sum_{i=1}^n |(\Phi x)_i - (\Phi y)_i|_0 < \varepsilon.$$

Thus, Φ is continuous.

Next, we show that Φ is compact. Set $a = \max_{1 \leq i \leq n} \sum_{j=1}^n \bar{a}_{ij}$. Let $M > 0$ be any constant and let $S = \{x \in X : \|x\| \leq M\}$ be a bounded set. For any $x \in S$, it follows from (2.8) and (2.9) that

$$|(\Phi x)_i|_0 \leq B_i \int_0^\omega |x_i(s)| \sum_{j=1}^n a_{ij}(s) |x_j(s - \tau_{ij}(s))| ds \leq \omega B M^2 \sum_{j=1}^n \bar{a}_{ij} \leq a \omega B M^2,$$

and so

$$\|\Phi x\| = \sum_{i=1}^n |(\Phi x)_i|_0 \leq n a \omega B M^2, \quad \forall x \in S.$$

Again, from (2.8), we have

$$[(\Phi x)_i(t)]' = r_i(t)(\Phi x)_i(t) - x_i(t) \sum_{j=1}^n a_{ij}(t) x_j(t - \tau_{ij}(t)), \quad i = 1, 2, \dots, n.$$

Then for $x \in S$,

$$\begin{aligned} |[(\Phi x)_i(t)]'| &\leq r_i(t)|(\Phi x)_i(t)| + |x_i(t)| \sum_{j=1}^n a_{ij}(t) |x_j(t - \tau_{ij}(t))| \\ &\leq r_i^u a \omega B M^2 + M^2 \sum_{j=1}^n a_{ij}^u \\ &\leq K M^2, \quad i = 1, 2, \dots, n, \end{aligned}$$

where $K = \max_{1 \leq i \leq n} (r_i^u a \omega B + \sum_{j=1}^n a_{ij}^u)$ and

$$r_i^u = \max_{t \in [0, \omega]} r_i(t), \quad a_{ij}^u = \max_{t \in [0, \omega]} a_{ij}(t), \quad i, j = 1, 2, \dots, n.$$

Hence, $\Phi S \subset X$ is a family of uniformly bounded and equi-continuous functions. By the Ascoli-Arzela Theorem (see, e.g., [20, p. 169]), the operator Φ is compact, and so it is completely continuous. The proof is completed. \square

We are now in a position to state and prove our main results of this paper.

Theorem 2.5. *Assume that (C) holds. Then Eq. (1.1) has at least one positive ω -periodic solution.*

Proof. Let $x^* = (x_1^*, x_2^*, \dots, x_n^*)^T$ with $x_i^* > 0$, $i = 1, 2, \dots, n$, be a positive solution of (1.5). Set

$$(2.11) \quad A = \min\{\bar{r}_i A_i : i = 1, 2, \dots, n\}, \quad B = \max\{\bar{r}_i B_i : i = 1, 2, \dots, n\}.$$

Then $0 < A < B < \infty$. Define

$$(2.12) \quad \Omega_1 = \left\{ x(t) = (x_1(t), x_2(t), \dots, x_n(t))^T \in X : |x_i|_0 < \frac{x_i^*}{B\omega}, i = 1, 2, \dots, n \right\}.$$

If $x = x(t) \in P \cap \partial\Omega_1$, then $\sigma|x_i|_0 \leq x_i(t) \leq |x_i|_0 = (B\omega)^{-1}x_i^*$, $i = 1, 2, \dots, n$, and

$$\begin{aligned} |(\Phi x)_i|_0 &\leq B_i \int_0^\omega x_i(s) \sum_{j=1}^n a_{ij}(s)x_j(s - \tau_{ij}(s))ds \\ &\leq B_i \omega |x_i|_0 \sum_{j=1}^n \bar{a}_{ij} |x_j|_0 \\ &= B_i \omega (B\omega)^{-1} |x_i|_0 \sum_{j=1}^n \bar{a}_{ij} x_j^* \\ &= B_i \bar{r}_i \omega (B\omega)^{-1} |x_i|_0 \\ &\leq |x_i|_0, \quad i = 1, 2, \dots, n, \end{aligned}$$

and so

$$(2.13) \quad \|\Phi x\| = \sum_{i=1}^n |(\Phi x)_i|_0 \leq \sum_{i=1}^n |x_i|_0 = \|x\|, \quad \forall x = x(t) \in P \cap \partial\Omega_1.$$

Next, we define

$$(2.14) \quad \Omega_2 = \left\{ x(t) = (x_1(t), x_2(t), \dots, x_n(t))^T \in X : |x_i| < \frac{x_i^*}{\sigma^2 A \omega}, i = 1, 2, \dots, n \right\}.$$

If $x = x(t) \in P \cap \partial\Omega_2$, then $\sigma|x_i|_0 \leq x_i(t) \leq |x_i|_0 = (\sigma^2 A \omega)^{-1}x_i^*$, $i = 1, 2, \dots, n$, and

$$\begin{aligned} (\Phi x)_i(t) &\geq A_i \int_0^\omega x_i(s) \sum_{j=1}^n a_{ij}(s)x_j(s - \tau_{ij}(s))ds \\ &\geq \sigma^2 A_i \omega |x_i|_0 \sum_{j=1}^n \bar{a}_{ij} |x_j|_0 \\ &= A_i \omega (A\omega)^{-1} |x_i|_0 \sum_{j=1}^n \bar{a}_{ij} x_j^* \\ &= A_i \bar{r}_i \omega (A\omega)^{-1} |x_i|_0 \\ &\geq |x_i|_0, \quad i = 1, 2, \dots, n, \end{aligned}$$

and so

$$(2.15) \quad \|\Phi x\| = \sum_{i=1}^n |(\Phi x)_i|_0 \geq \sum_{i=1}^n |x_i|_0 = \|x\|, \quad \forall x = x(t) \in P \cap \partial\Omega_2.$$

Obviously, Ω_1 and Ω_2 are open bounded subsets of X with $0 \in \Omega_1 \subset \bar{\Omega}_1 \subset \Omega_2$. Hence, $\Phi : P \cap (\bar{\Omega}_2 \setminus \Omega_1) \rightarrow P$ is a completely continuous operator and satisfies

condition (i) in Lemma 2.2. By Lemma 2.2, there exists a point $x = x(t) \in P \cap (\bar{\Omega}_2 \setminus \Omega_1)$ such that $x(t) = (\Phi x)(t)$, i.e., $x(t)$ is a positive ω -periodic solution of Eq. (1.1). The proof is completed. \square

Theorem 2.6. *Assume that $a_{ii}(t) \equiv a_{ij} \geq 0, \tau_{ij}(t) \equiv \tau_{ij}, i, j = 1, 2, \dots, n$. Then Eq. (1.1) has at least one positive ω -periodic solution if and only if the system of linear equations*

$$(2.16) \quad \sum_{j=1}^n a_{ij} x_j = \bar{r}_i, \quad i = 1, 2, \dots, n,$$

has a positive solution.

Proof. If (2.16) has a positive solution, then by Theorem 2.5, Eq. (1.1) has at least one positive ω -periodic solution. On the other hand, if Eq. (1.1) has at least one positive ω -periodic solution, say $x(t) = (x_1(t), x_2(t), \dots, x_n(t))^T$. Then from (1.1), we have

$$\int_0^\omega \left[r_i(t) - \sum_{j=1}^n a_{ij} x_j(t - \tau_{ij}) \right] dt = 0, \quad i = 1, 2, \dots, n.$$

It follows that

$$\sum_{j=1}^n a_{ij} \left(\frac{1}{\omega} \int_0^\omega x_j(t) dt \right) = \bar{r}_i, \quad i = 1, 2, \dots, n.$$

This shows that the system (2.16) of linear equations has a positive solution $x_j = \frac{1}{\omega} \int_0^\omega x_j(t) dt, j = 1, 2, \dots, n$. The proof is completed. \square

Remark 2.7. The method in this paper may be used to more general Lotka-Volterra competition systems than Eq. (1.1).

REFERENCES

- [1] C. Alvarez, A. C. Lazer, *An application of topological degree to the periodic competing species model*, J. Austral. Math. Soc. Ser. B 28(1986), 202-219. MR0862570 (87k:34062)
- [2] S. Ahmad, *On the nonautonomous Lotka-Volterra competition equations*, Proc. Amer. Math. Soc. 117(1993), 199-204. MR1143013 (93c:34109)
- [3] A. Battaaz, F. Zanolin, *Coexistence states for periodic competition Kolmogorov systems*, J. Math. Anal. Appl. 219(1998), 179-199. MR1606377 (98m:34086)
- [4] Y. Chen, Z. Zhou, *Stable periodic solution of a discrete periodic Lotka-Volterra competition system*, J. Math. Anal. Appl. 277(2003), 358-366. MR1954481 (2004k:39032)
- [5] J. M. Cushing, *Two species competition in a periodic environment*, J. Math. Biol. 10(1980), 385-400. MR0602256 (82c:92017)
- [6] M. Fan, K. Wang, *Global Periodic Solutions of a Generalized n -Species Gilpin-Ayala Competition Model*, Computers Math. Applic. 40(2000), 1141-1151. MR1784658 (2001i:92043)
- [7] M. Fan, K. Wang, D. Q. Jiang, *Existence and global attractivity of positive periodic solutions of periodic n -species Lotka-Volterra competition systems with several deviating arguments*, Math. Biosci. 160(1999), 47-61. MR1704338 (2000f:92016)
- [8] H. I. Freedman, P. Waltman, *Persistence in a model of three competitive populations*, Math. Biosci. 73(1985), 89-101. MR0779763 (86i:92038)
- [9] K. Gopalsamy, *Global asymptotical stability in a periodic Lotka-Volterra system*, J. Austral. Math. Soc. Ser. B 24(1982), 160-.
- [10] K. Gopalsamy, *Global asymptotical stability in a periodic Lotka-Volterra system*, J. Austral. Math. Soc. Ser. B 29(1985), 66-72.
- [11] K. Gopalsamy, *Stability and Oscillation in Delay Differential Equations of Population Dynamics*, Kluwer Academic Publishers, Dordrecht, 1992. MR1163190 (93c:34150)

- [12] I. Györy, G. Ladas, *Oscillation Theory of Delay Differential Equations*, Oxford Science, Oxford, 1991. MR1168471 (93m:34109)
- [13] M. A. Krasnoselskii, *Positive Solutions of Operator Equations*, Noordhoff, Groningen, 1964. MR0181881 (31:6107)
- [14] P. Korman, *Some new results on the periodic competition model*, J. Math. Anal. Appl. 171(1992), 131-138. MR1192498 (93j:92033)
- [15] Y. Kuang, *Delay Differential Equations with Applications in Population Dynamics*, Academic Press, Boston, 1993. MR1218880 (94f:34001)
- [16] Y. K. Li, *Periodic solutions of N -species competition system with delays*, J. Biomath. 12(1997), 1-12. MR1460907 (99f:92021)
- [17] Y. K. Li, *On a periodic delay logistic type population model*, Ann. of Diff. Eqs. 14(1998), 29-36. MR1633664 (99d:34133)
- [18] Y. K. Li, *Periodic solutions for delay Lotka-Volterra competition systems*, J. Math. Anal. Appl. 246(2000), 230-244. MR1761160 (2001b:34132)
- [19] Y. K. Li, Y. Kuang, *Periodic solutions of periodic delay Lotka-Volterra equations and systems*, J. Math. Anal. Appl. 255(2001), 260-280. MR1813821 (2001k:34133)
- [20] H. L. Roydin, *Real Analysis*, Macmillan Publishing Company, New York, 1988. MR1013117 (90g:00004)
- [21] A. Shibata, N. Saito, *Time delays and chaos in two competition system*, Math. Biosci. 51(1980), 199-211. MR0587228 (81m:92054)
- [22] H. L. Smith, *Periodic solutions of periodic competitive and cooperative systems*, SIAM J. Math. Anal. 17(1986), 1289-1318. MR0860914 (87m:34057)
- [23] H. L. Smith, *Periodic competitive differential and the discrete dynamics of a competitive map*, J. Different. Eq. 64(1986), 165-194. MR0851910 (87k:92027)
- [24] A. Trieo, C. Alvarez, *A different consideration about the globally asymptotically stable solution of the periodic n -competing species problem*, J. Math. Anal. Appl. 159(1991), 44-50. MR1119420 (93d:34080)
- [25] X. H. Tang and X. Zou, *$3/2$ -type criteria for global attractivity of Lotka-Volterra competition system without instantaneous negative feedback*, J. Differential Equations, 186(2002), 420-439. MR1942216 (2003k:34138)
- [26] X. H. Tang and X. Zou, *Global attractivity of non-autonomous Lotka-Volterra competition system without instantaneous negative feedbacks*, J. Differential Equations, 192(2003), 502-535. MR1990850 (2004e:34116)

SCHOOL OF MATHEMATICAL SCIENCES AND COMPUTING TECHNOLOGY, CENTRAL SOUTH UNIVERSITY, CHANGSHA, HUNAN 410083, PEOPLE'S REPUBLIC OF CHINA
E-mail address: tangxh@mail.csu.edu.cn

DEPARTMENT OF APPLIED MATHEMATICS, UNIVERSITY OF WESTERN ONTARIO, LONDON, ONTARIO, CANADA N6A 5B7
E-mail address: xzou@uwo.ca